
Program verification using Verification-Condition generation

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Outline

- **From Programs to SMT formulas**
 - ⊙ **Straight line programs**
- **Annotations**
 - ⊙ **Loops and Procedures**
- **Modeling low-level C programs**
- **HAVOC toolkit**
- **Challenges for scalable and automated verification**

Program Correctness: Hoare Triple

- Hoare triple

{P} S {Q}

P, Q : predicates/property

S : a program

- From a state satisfying P, if S executes, then either:
 - ⊙ Either S does not terminate, or
 - ⊙ S terminates in a state satisfying Q

Program verification \rightarrow Formula

$\{ b.f = 5 \} a.f = 5 \{ a.f + b.f = 10 \}$

is valid

iff

$\text{Select}(f1,b) = 5 \wedge f2 = \text{Store}(f1,a,5) \Rightarrow \text{Select}(f2,a) + \text{Select}(f2,b) = 10$

is valid

theory of equality: $f, =$

theory of arithmetic: $5, 10, +$

theory of arrays: $\text{Select}, \text{Store}$

- [Nelson & Oppen '79]

Satisfiability-Modulo-Theory (SMT)

- **Boolean satisfiability solving + theory reasoning**
- **Ground theories**
 - ⊙ Equality, arithmetic, Select/Store
- **NP-complete logics**

- **Phenomenal progress in the past few years**
 - ⊙ Yices [Dutretre&deMoura'06],
 - ⊙ Z3 [deMoura&Bjorner'07]

Simple prog. language (BoogiePL)

[Leino et al.'05]

● Commands

⊙ $x := E$

- evaluate E and change x to that value

⊙ **havoc** x

- change x to an arbitrary value

⊙ **assert** E

- if E holds, terminate; otherwise, go wrong

⊙ **assume** E

- if E holds, terminate; otherwise, block

⊙ $S ; T$

- execute S , then T

⊙ **goto** A or B ;

- change point of control to block A or block B , choosing blindly

Variables and Assignments

- **Two types of variables**

- **Scalar** (e.g. int, bool,...)

- **Maps** (mutable arrays, n-dimensional)

```
var y: int;
```

```
var a: [int] int;    // array variable
```

```
start:
```

```
    y := 10;           // assignment to scalar
```

```
    a[y] := 20;        // sugar for a := update(a, y, 20) ;
```

```
    y := a[10];       //read from a map
```

Example translation: if-then-else

[[if P then S else T end]]

\approx

Start: goto Then or Else

Then: assume P ;
 [[S]] ;
 goto After

Else: assume $\neg P$;
 [[T]] ;
 goto After

After: ...

Programs → Formulas

- Assume no loops (back-edge gotos)

$\{P\} S \{Q\}$



assume P; S; **assert** Q

- Task: Transform a program with **assume/assert** into a formula
 - ⦿ Known as *Verification Condition* (VC) generation

Verification-condition generation

1. passive features: **assert**, **assume**, **;**
2. state changes: **:=**, **havoc**
3. control flow: **goto** (no loops)

Weakest (liberal) precondition

- The *weakest liberal precondition* of a statement S with respect to a predicate Q on the post-state of S , denoted $wp(S, Q)$, is the set of pre-states from which execution:
 - ⦿ does not go wrong (by failing an **assert**), and
 - ⦿ if it terminates, terminates in Q

VC generation: passive features

- $\text{wp}(\text{assert } E, Q) = E \wedge Q$
- $\text{wp}(\text{assume } E, Q) = E \Rightarrow Q$
- $\text{wp}(S; T, Q) = \text{wp}(S, \text{wp}(T, Q))$

Eliminate :=, havoc

- Dynamic single assignment (DSA) form
 - ⊙ There is at most one definition for each variable on each path
 - ⊙ Replace defs/uses with new incarnations
 - $x := x+1$ with $x_{n+1} := x_n + 1$
 - ⊙ At join points unify variable incarnations
- Replace **havoc x** with new incarnations x_{n+1}
- *Eliminate assignments* by replacing $x := E \rightarrow \text{assume } x = E$

Example

```
assume x = 1;
```

```
x := x + 1;
```

```
if (x = 0) {
```

```
    x := x + 2;
```

```
} else {
```

```
    x := x + 3;
```

```
}
```

```
assert x = 5;
```

```
assume x0 = 1;
```

```
assume x1 = x0 + 1;
```

```
if (x1 = 0) {
```

```
    assume x2 = x1 + 2;
```

```
    assume x4 = x2;
```

```
} else {
```

```
    assume x3 = x1 + 3;
```

```
    assume x4 = x3;
```

```
}
```

```
assert x4 = 5;
```

Example

```
assume  $x_0 = 1$ ;  
assume  $x_1 = x_0 + 1$ ;  
  
if ( $x_1 = 0$ ) {  
    assume  $x_2 = x_1 + 2$ ;  
    assume  $x_4 = x_2$ ;  
} else {  
    assume  $x_3 = x_1 + 3$ ;  
    assume  $x_4 = x_3$ ;  
}  
assert  $x_4 = 5$ ;
```

```
start:  assume  $x_0 = 1$ ; goto  $l_1$ ;  
  
 $l_1$ :  assume  $x_1 = x_0 + 1$ ; goto  $l_2, l_3$ ;  
  
 $l_2$ :  assume  $x_1 = 0$ ;  
        assume  $x_2 = x_1 + 2$ ;  
        assume  $x_4 = x_2$ ; goto  $l_4$ ;  
  
 $l_3$ :  assume  $x_1 \neq 0$ ;  
        assume  $x_3 = x_1 + 3$ ;  
        assume  $x_4 = x_3$ ; goto  $l_4$ ;  
  
 $l_4$ :  assert  $x_4 = 5$ 
```

Control flow

- Finally, program is a collection of blocks
- Each block is
 - ⊙ $l: A_1, \dots, A_m; \text{ goto } l_1, \dots, l_n$
 - ⊙ l is block label
 - ⊙ A is either assume E or assert E
- Distinguished “start” label

VC Generation for Unstructured Control Flow

For each block $A \cong I: S; \text{goto } I_1, \dots, I_n$

1. Introduce a boolean variable A_{ok}
 - A_{ok} holds iff all executions starting at A do not end in a failed assertion
2. Introduce a Block Equation for each block A :

$$BE_A \cong A_{ok} \Leftrightarrow VC(S, \bigwedge_{B \in \text{Succ}(A)} B_{ok})$$

VC of entire program:

$$(\bigwedge_A BE_A) \Rightarrow \text{Start}_{ok}$$

VC Generation

A	{ start: assume $x_0 = 1$; goto l_1 ;	$A_{ok} \Leftrightarrow (x_0 = 1 \Rightarrow B_{ok})$	\wedge
B	{ l_1 : assume $x_1 = x_0 + 1$; goto l_2, l_3 ;	$B_{ok} \Leftrightarrow (x_0 = 1 \Rightarrow C_{ok} \wedge D_{ok})$	\wedge
C	{ l_2 : assume $x_1 = 0$; assume $x_2 = x_1 + 2$; assume $x_4 = x_2$; goto l_4 ;	$C_{ok} \Leftrightarrow (x_1 = 0 \Rightarrow$ $(x_2 = x_1 + 2 \Rightarrow$ $(x_4 = x_2 \Rightarrow E_{ok})))$	\wedge
D	{ l_3 : assume $x_1 \neq 0$; assume $x_3 = x_1 + 3$; assume $x_4 = x_3$; goto l_4 ;	$D_{ok} \Leftrightarrow (x_1 \neq 0 \Rightarrow$ $(x_2 = x_1 + 2 \Rightarrow$ $(x_4 = x_3 \Rightarrow E_{ok})))$	\wedge
E	{ l_4 : assert $x_4 = 5$	$E_{ok} \Leftrightarrow (x_4 = 5 \wedge \text{true})$	\wedge
		$\Rightarrow A_{ok}$	

VC Generation

Formula over
Arithmetic, Equality,
and Boolean
connectives

Can be solved by
a SMT solver

$$A_{ok} \Leftrightarrow (x_0 = 1 \Rightarrow B_{ok}) \quad \wedge$$

$$B_{ok} \Leftrightarrow (x_0 = 1 \Rightarrow C_{ok} \wedge D_{ok}) \quad \wedge$$

$$C_{ok} \Leftrightarrow (x_1 = 0 \Rightarrow \\ (x_2 = x_1 + 2 \Rightarrow \\ (x_4 = x_2 \Rightarrow E_{ok}))) \quad \wedge$$

$$D_{ok} \Leftrightarrow (x_1 \neq 0 \Rightarrow \\ (x_2 = x_1 + 2 \Rightarrow \\ (x_4 = x_3 \Rightarrow E_{ok}))) \quad \wedge$$

$$E_{ok} \Leftrightarrow (x_4 = 5 \wedge \text{true}) \quad \wedge$$

$$\Rightarrow A_{ok}$$

Summary: VC Generation

- From programs \rightarrow logical formulas
- Efficient VC generation
 - A formula that is *linear* in the size of the (loop-free and call-free) program
- Language of assertion determines the logical theories for the VC

Loops and procedure calls

- Transform loops to loop-free programs
 - ⦿ With *loop-invariants*
- Transform procedure calls into asserts and assumes
 - ⦿ With *preconditions* and *postconditions*

Example translation: loop

```
[[ while { invariant J } B do S end ]]
```

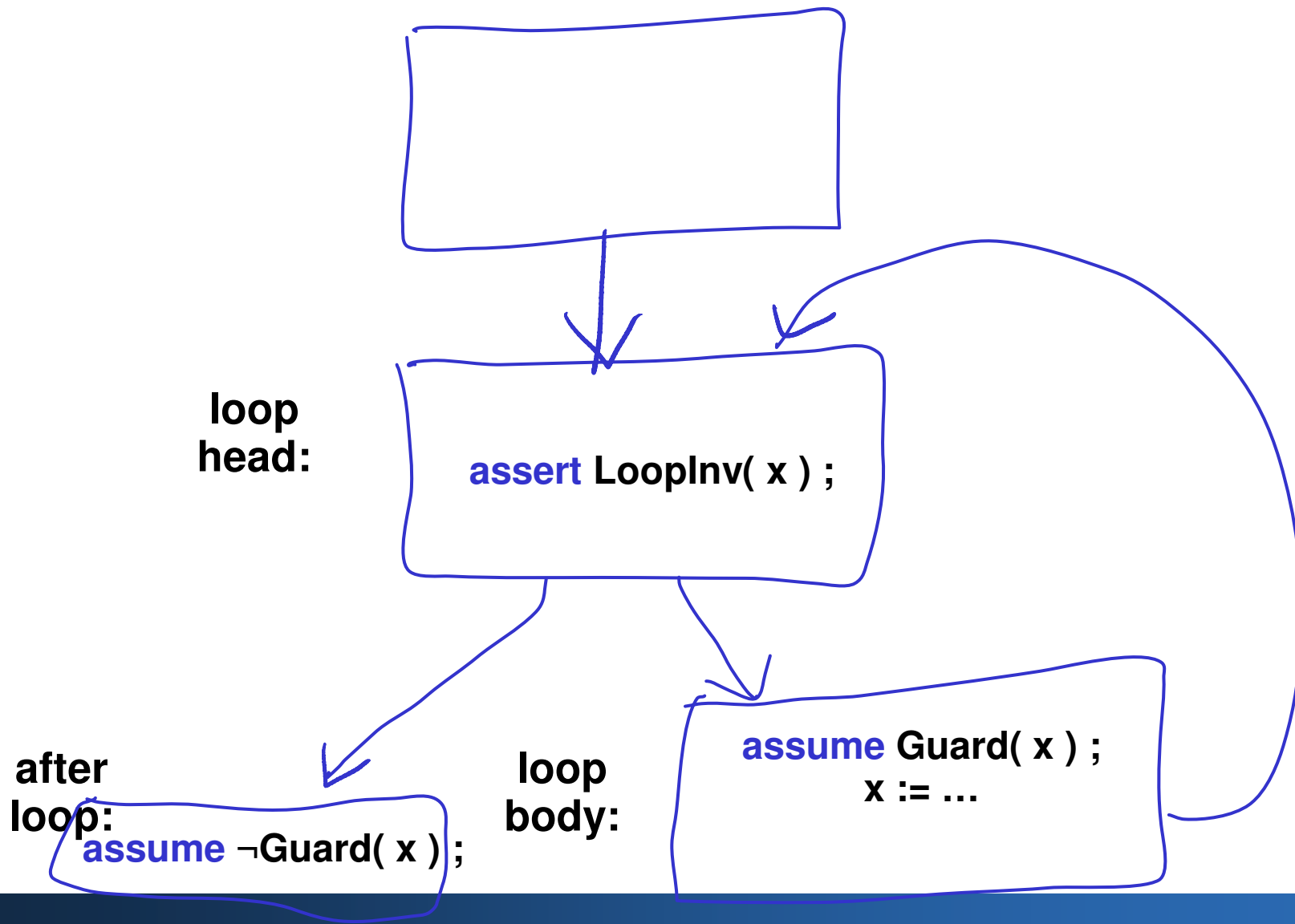
\approx

```
LoopHead:    assert J ;  
             goto LoopBody or AfterLoop
```

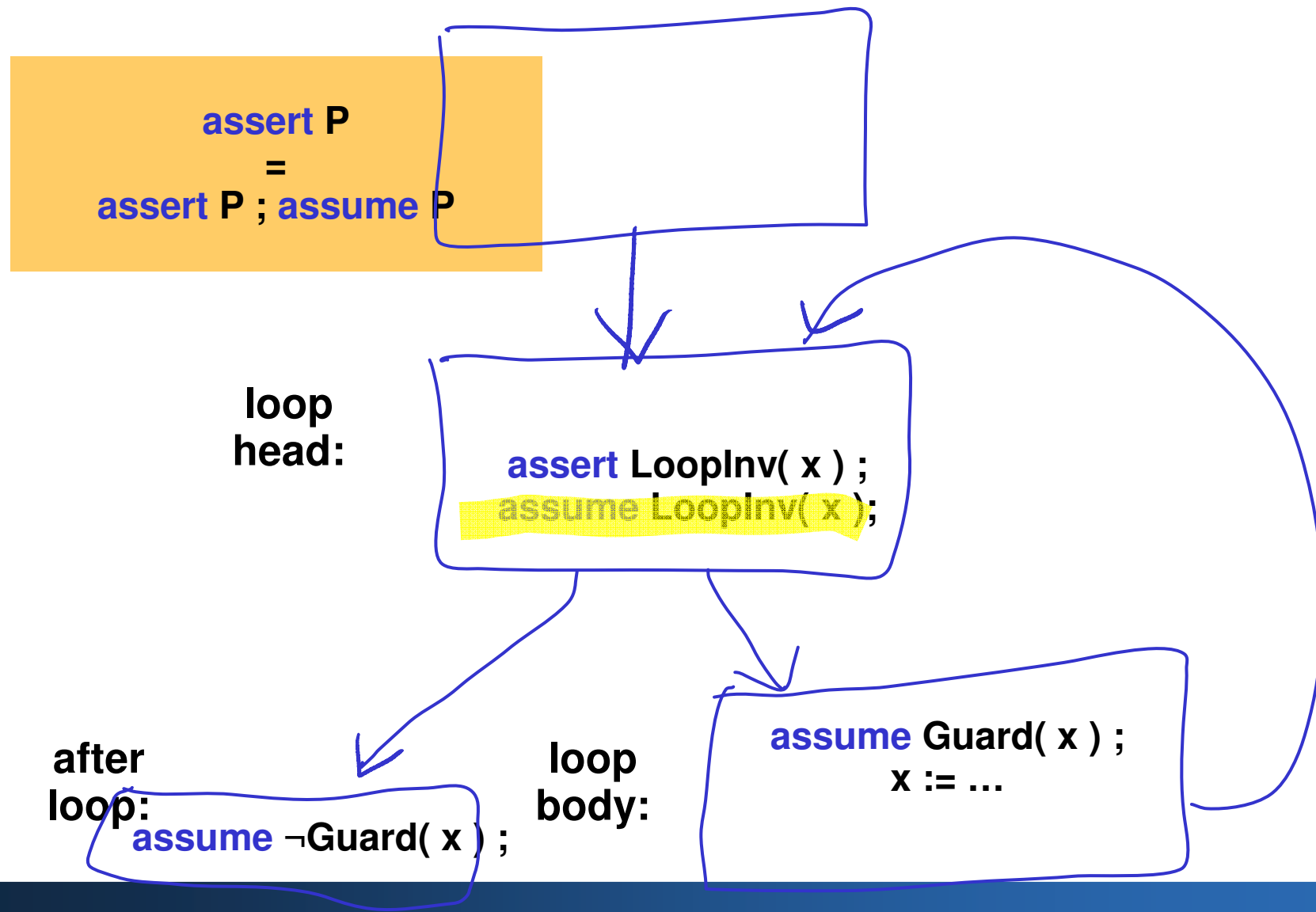
```
LoopBody:    assume B ;  
             [[ S ]];  
             goto LoopHead
```

```
AfterLoop:   assume  $\neg$ B ;  
             ...
```

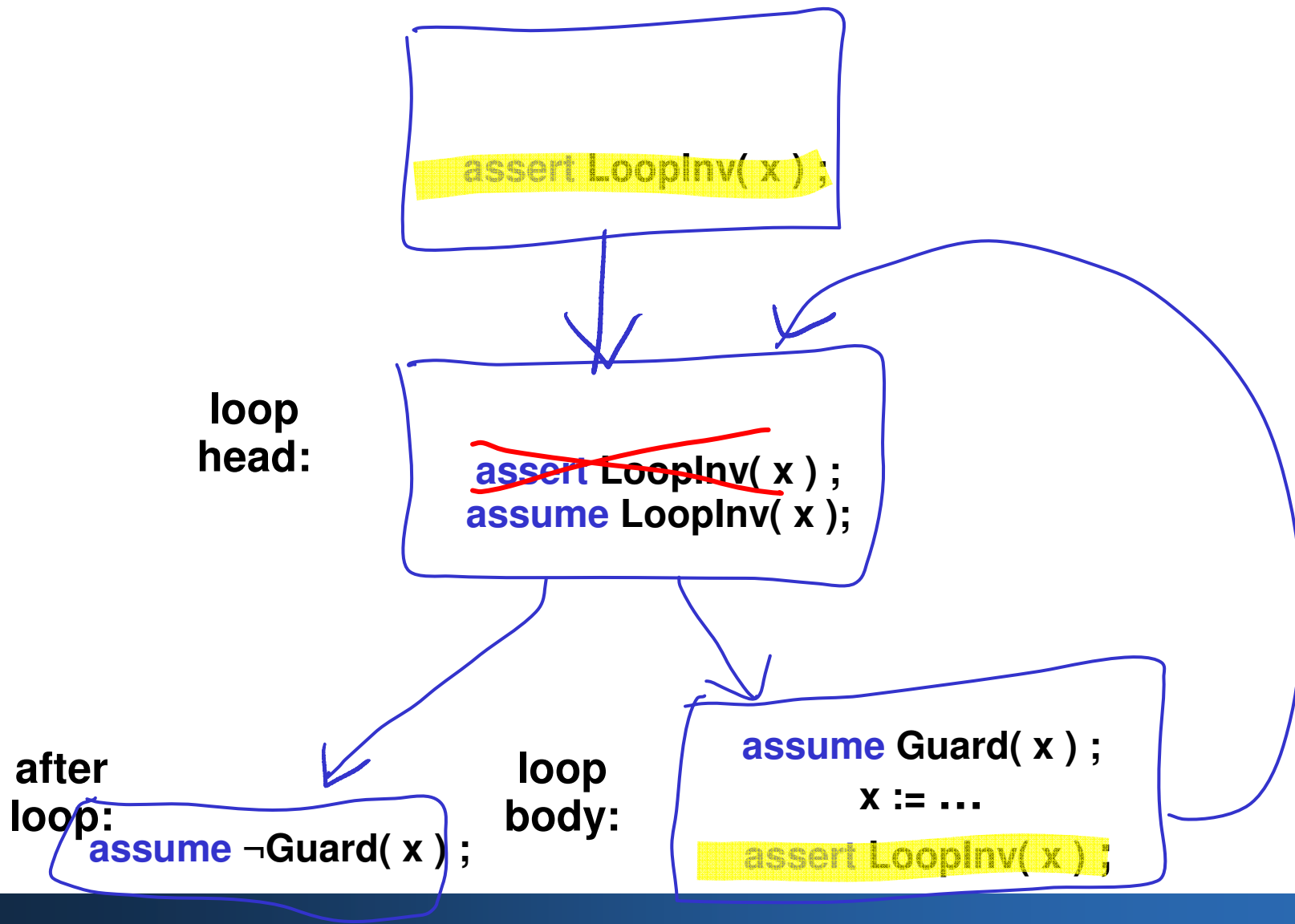
Transforming loops



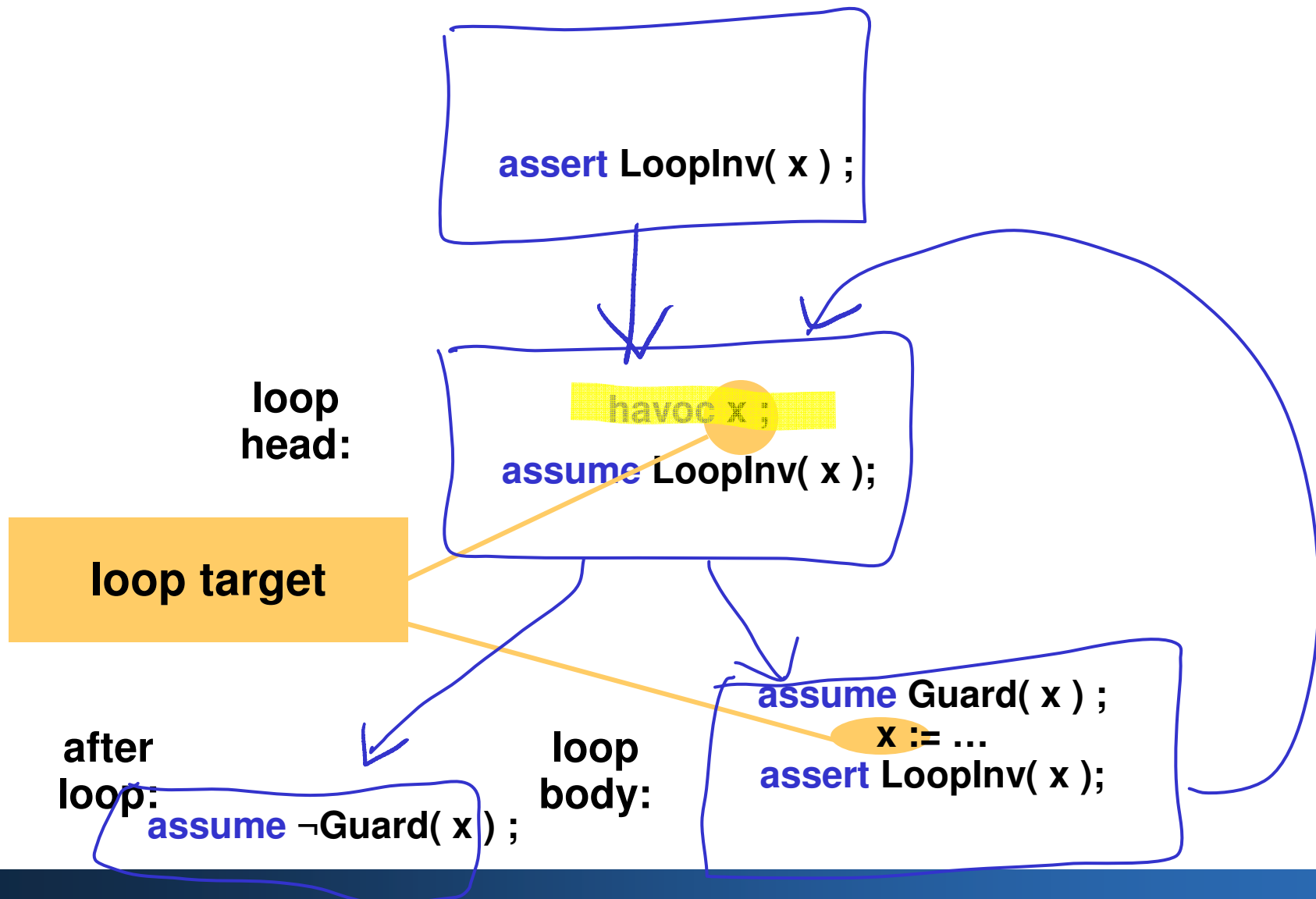
Transforming loops



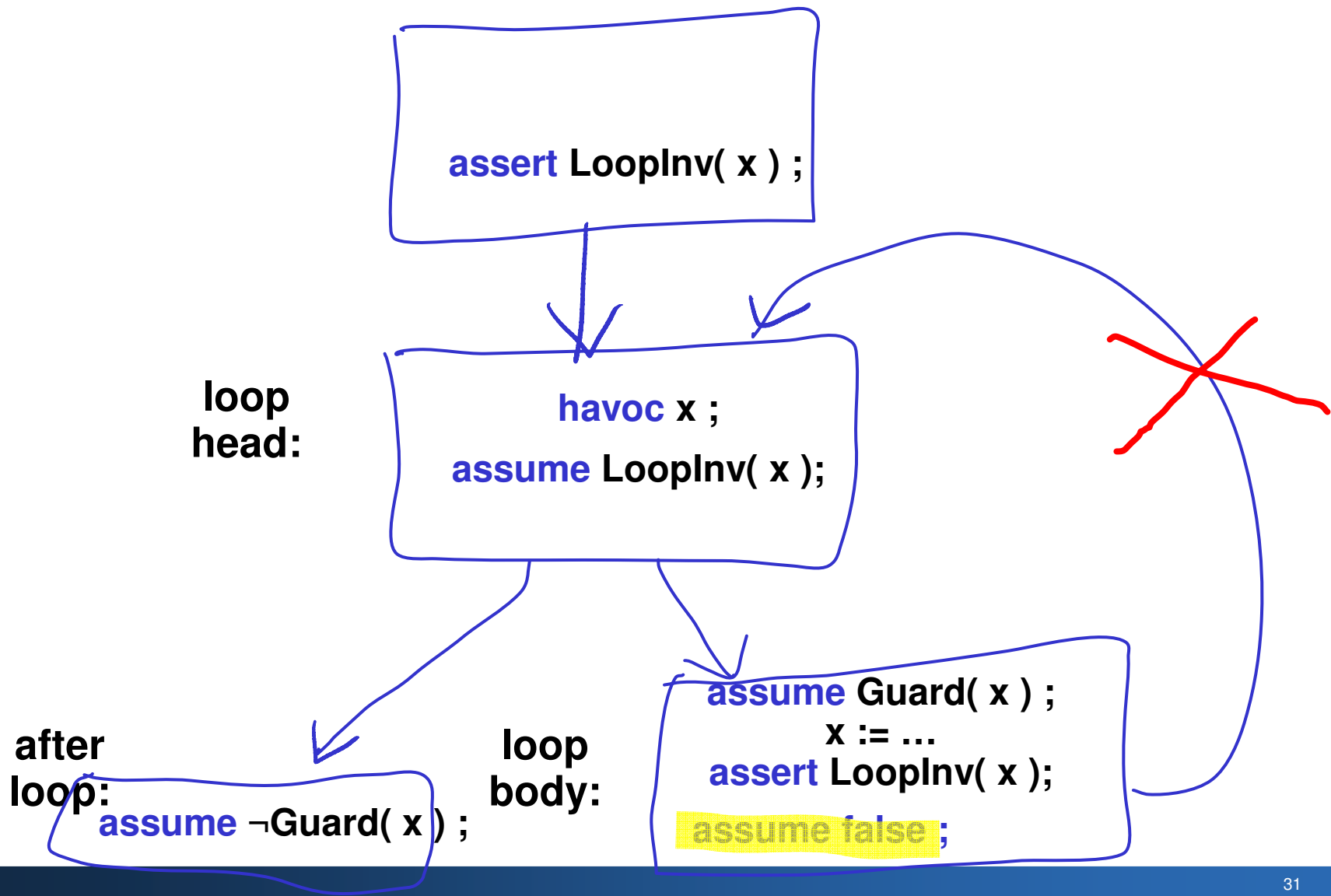
Transforming loops



Transforming loops

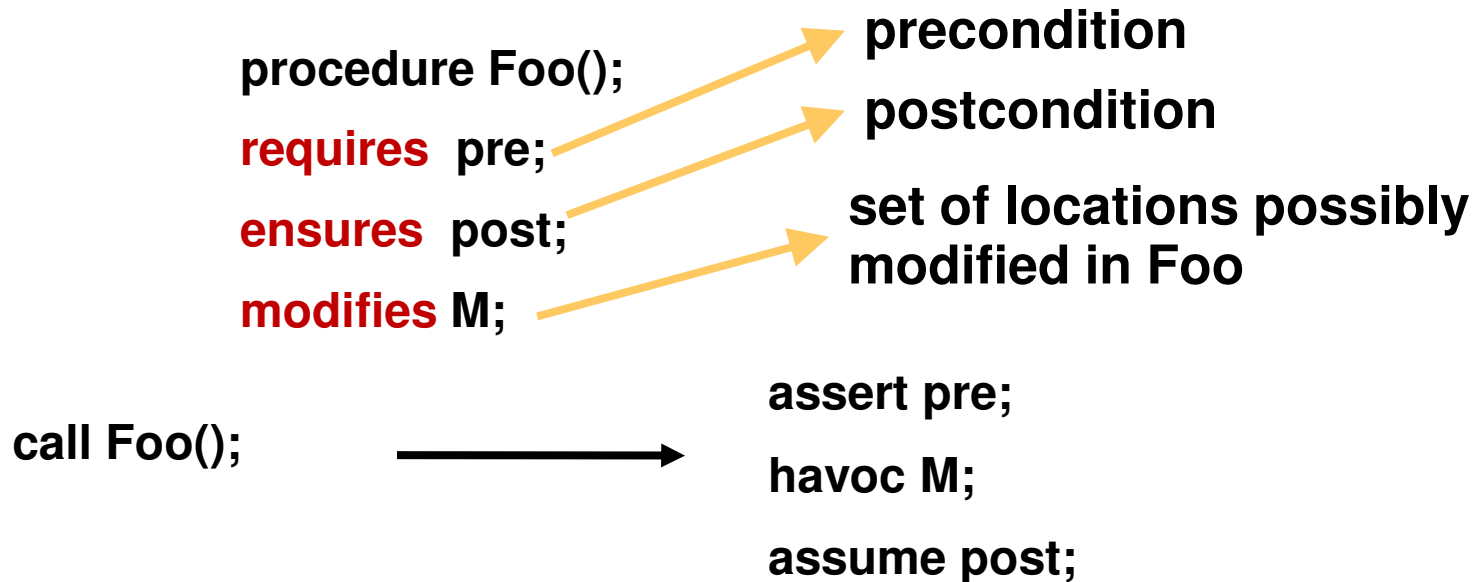


Transforming loops



What about procedure calls?

- Each procedure verified separately
- Procedure calls replaced with their specifications



Example of loop invariant + procedure contract

```
int x, y; //globals
```

```
void main(){
```

```
    x := y := 0;
```

```
    Foo(4);
```

```
    assert (x = 5); // should fail
```

```
    assert (x = 4); //should pass
```

```
}
```

```
requires n >= 0;
```

```
ensures x = n;
```

```
modifies x;
```

```
void Foo(int n){
```

```
    x := 0; y := n;
```

```
invariant( y >= 0  $\wedge$  x + y = n)
```

```
    while(y > 0) {
```

```
        x++;
```

```
        y--;
```

```
    }
```

```
}
```



Summary

- **VC generation**
 - ⦿ **Generates a SMT formula from loop/call free code**
- **Loop invariants**
 - ⦿ **Transform loops to loop-free code**
- **Procedure contracts**
 - ⦿ **Transform procedure calls to call-free code**

Modeling C

- **Convert C to BoogiePL**
 - ⊙ **A memory model to model C's operations**
 - ⊙ **Using the HAVOC toolkit**
- **Generate formulas using Boogie VC generator**

C language

C types

- ⦿ Scalars (int, long, char, short)
- ⦿ Pointers (int*, struct T*, ..)
- ⦿ Nested structs and unions
- ⦿ Array (struct T a[10];)
- ⦿ Function pointers
- ⦿ Void *

Difficult to establish type safety in presence of pointer arithmetic, casts

C language (cont.)

Operations

- ⊙ **Arithmetic and Relational (+, -, ≤, =..)**
- ⊙ **Pointer arithmetic ((T*) x ++)**
- ⊙ **Address-of (&) operation**
 - **Allows taking address of fields and nested structures**
- ⊙ **Allocate and free**
- ⊙ **Casts**

Memory Model in HAVOC

- **Every pointer (address or value) is an integer**
- **Pointer dereference modeled as lookups/updates to a map **Mem****
- **Accounts for pointer arithmetic, internal pointers, address-of operations, arrays, casts, ...**

Memory model

- Maps (in BoogiePL) for memory model

// Mutable

Mem: int \rightarrow int

Alloc: int \rightarrow {UNALLOCATED, ALLOCATED, FREED}

// Immutable

Base: int \rightarrow int //base address of each pointer

Type: int \rightarrow type //type of each pointer

C Variable → Boogie Variable

- Variables are *usually* allocated in the heap/Mem
 - ⊙ To account for the address of a variable (e.g. $y = \&x$)
 - ⊙ To deal with structure/union variables
 - `struct T { int f; int g;} x;`
 - ⊙ All globals are allocated on the heap (make the translation modular)
- Only scalar locals and parameters whose addresses haven't been taken are mapped to BoogiePL variables

C → BoogiePL

```
typedef struct {  
  int g[10]; int f;} DATA;  
  
DATA *create() {  
  int a;  
  
  DATA *d = (DATA*)  
  malloc(sizeof(DATA));  
  init(d->g, 10, &a);  
  
  d->f = a;  
  d->g[1] = 2;  
  
  return d;  
}
```

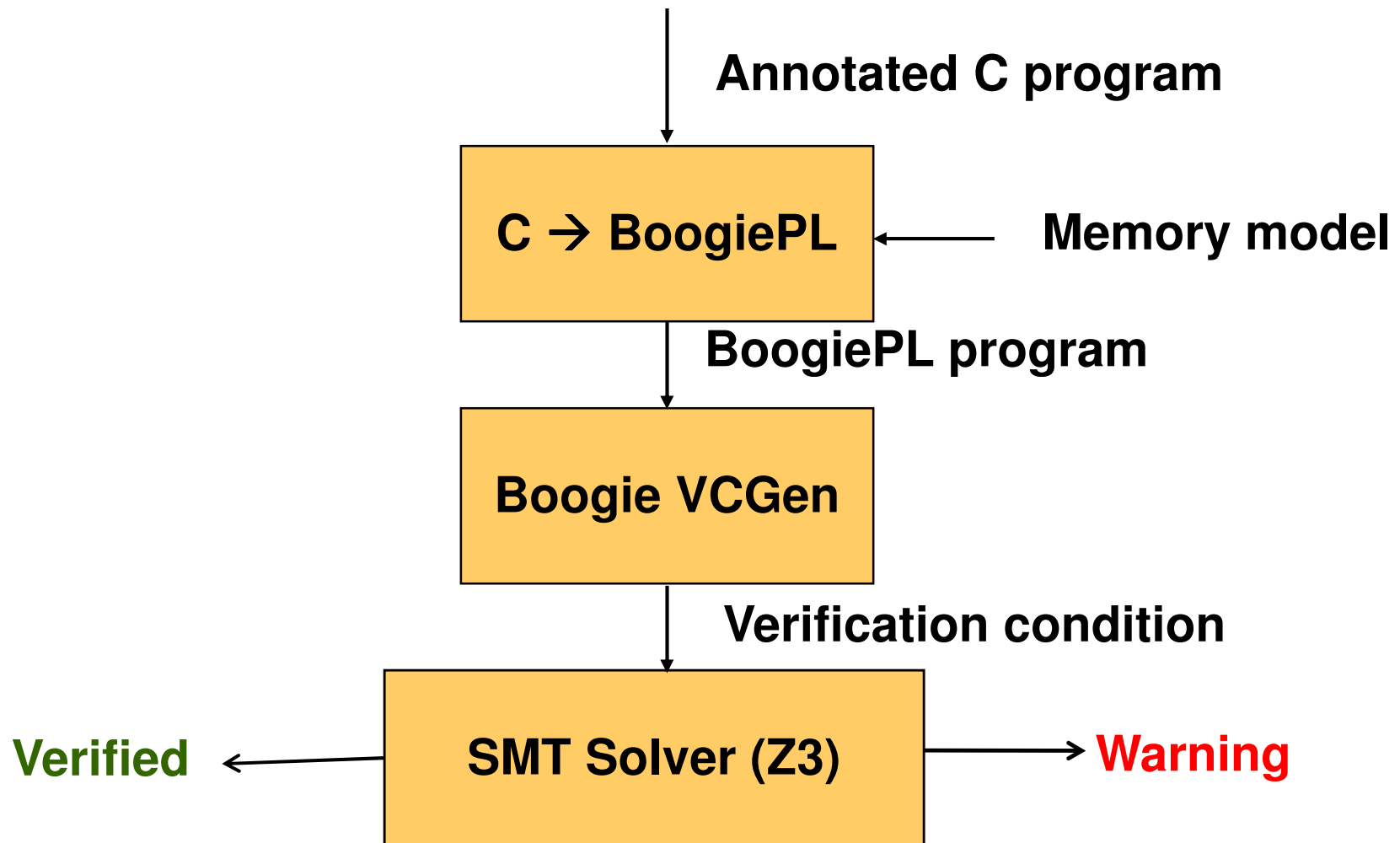
```
function f_DATA: int -> int;  
forall u: int:: f_DATA(u) = u + 40;  
  
procedure create() returns d:int{  
  var @a: int;  
  @a := malloc(4);  
  d := call malloc(44);  
  
  call init(g_DATA(d), 10, @a);  
  
  Mem[f_DATA(d)] := Mem[@a];  
  Mem[g_DATA(d) + 1*4] := 2;  
  free(@a);  
  return;  
}
```

HAVOC

Assertion checker for low-level (C) systems programs (kernel, device drivers, etc.)

- 1. Precise** modeling of the heap
 - Internal pointers, pointer arithmetic, casts, lists, arrays, ..
- 2. Expressive** annotation language for C
 - Deal with linked lists, arrays, types
- 3. Automated and efficient** reasoning using SMT solvers + decision procedures for heap

HAVOC Flow

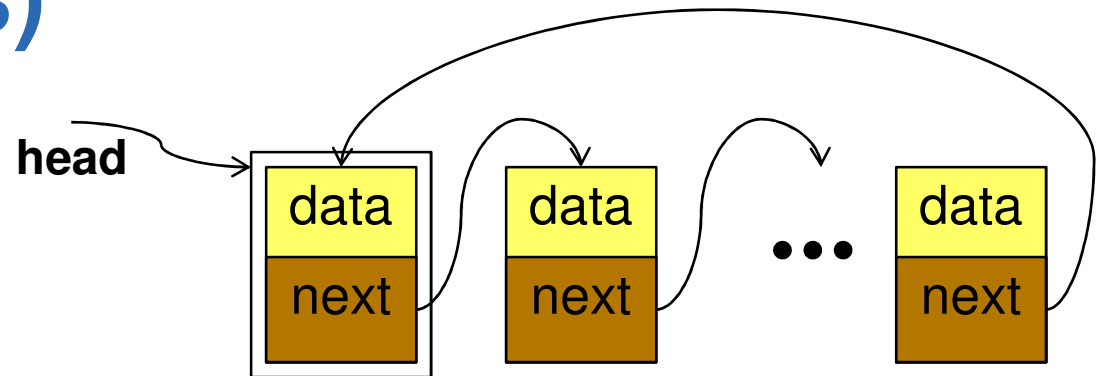


Challenges

- **Expressive yet efficient logic to specify properties**
 - ⦿ **Properties about lists, arrays,**
 - ⦿ **Yet amenable to automated SMT solvers**
- **Annotation inference**
 - ⦿ **Infer procedure contracts and loop invariants**

Example (lists)

```
typedef struct _DATA {  
    int data;  
    struct _DATA *next;  
} DATA, *PDATA;
```



Possible null
dereference !!

Need to
understand
lists

```
void InitializeList(PDATA head) {
```

```
    PDATA iter;  
    iter = head->next;
```

```
    while (iter != head) {
```

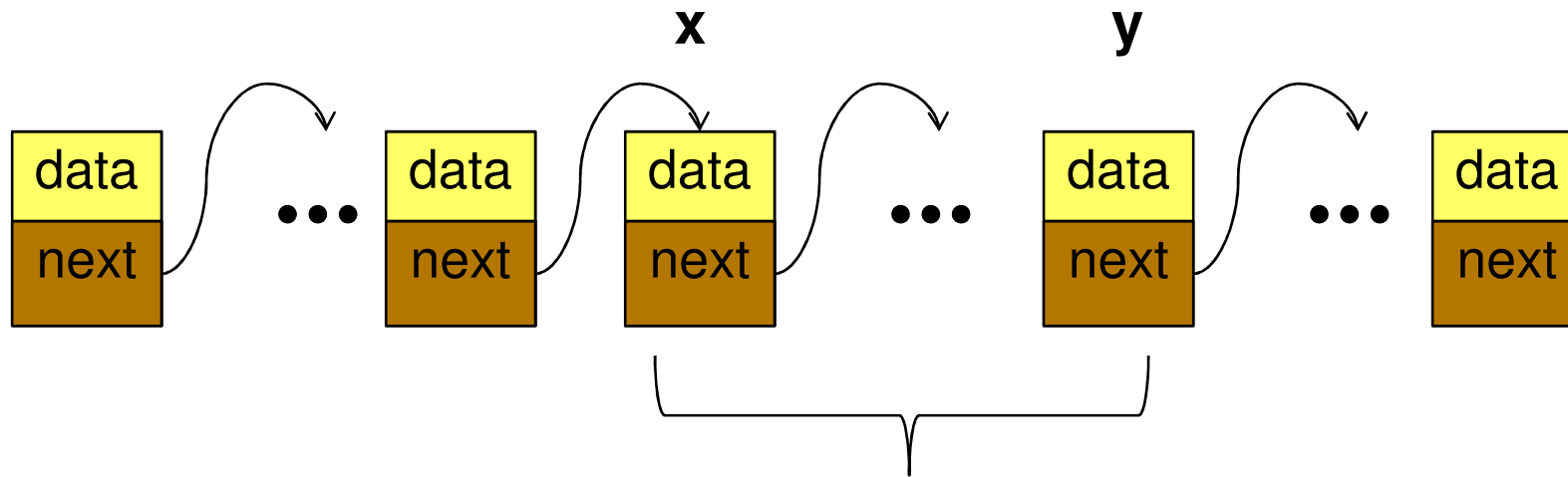
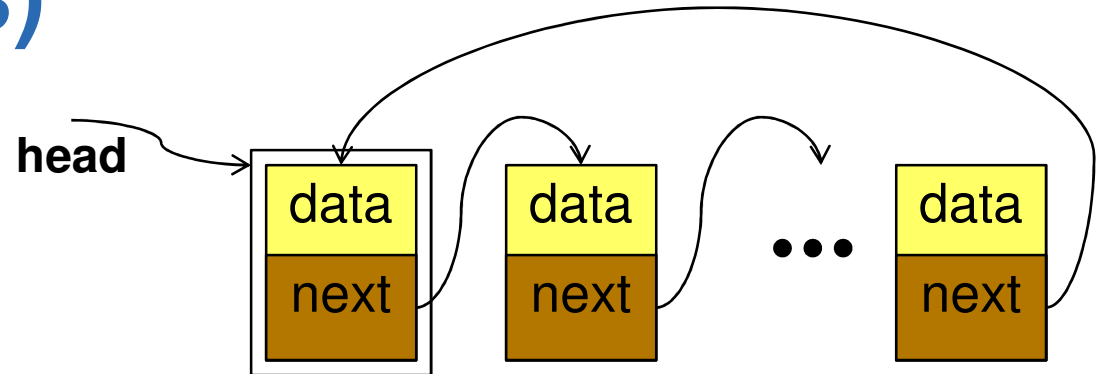
```
        iter->data = 5;  
        iter = iter->next;
```

```
    }  
}
```

45

Example (lists)

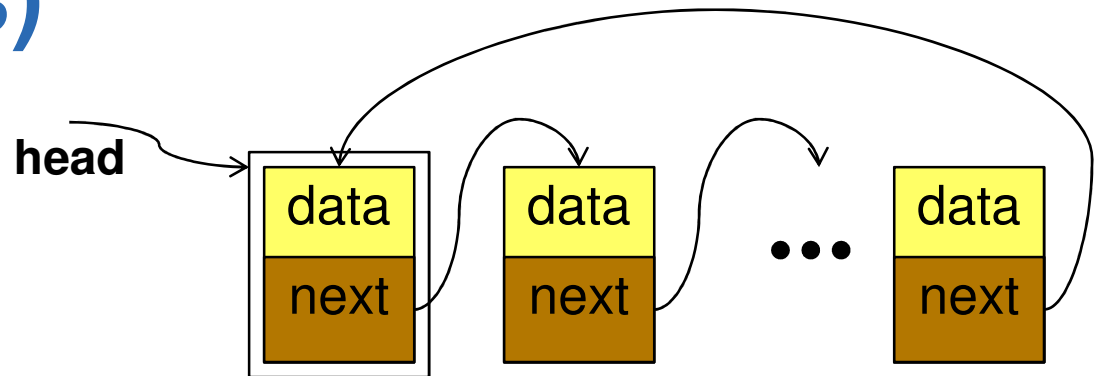
```
typedef struct _DATA {  
  int data;  
  struct _DATA *next;  
} DATA, *PDATA;
```



Btwn(next, x, y)

Example (lists)

```
typedef struct _DATA {  
  int data;  
  struct _DATA *next;  
} DATA, *PDATA;
```



requires ($head \in \text{Btwn}(\text{next}, \text{head} \rightarrow \text{next}, \text{head})$)

void InitializeList(PDATA head) {

PDATA iter;
iter = head->next;

invariant($iter \in \text{Btwn}(\text{next}, \text{head} \rightarrow \text{next}, \text{head})$)

while (iter != head) {

```
  iter->data = 5;  
  iter = iter->next;
```

```
  }  
}
```

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Possible null
dereference !!

Need to
understand
lists

Annotation inference

- **Currently semi-automatic**
 - ⊙ **Can infer simple annotations**
 - ⊙ **Needs user to provide complex annotations**

- **Houdini algorithm (from ESC/JAVA) [Flanagan&Leino '01]**
 - ⊙ **User “guesses” a candidate annotation for all the procedures in a module**
 - Parameters non-null
 - Locks are unheld on entry and exit
 - ⊙ **The tool prunes away the annotations that may be violated using an SMT solver**
 - More examples on HAVOC webpage

Applications of HAVOC

- **Functional correctness of medium sized programs with lists and arrays (e.g. custom allocators)**
 - ⊙ POPL'08
- **Complex synchronization properties of a core Windows component**
 - ⊙ ~300KLOC, ~1500 procedure
 - ⊙ 40+ bugs found with only 600L of manual annotations
 - ⊙ Annotations allow documentation and incremental checking
- **Type checking of low-level C code**
 - ⊙ Device drivers ~1KLOC,

HAVOC is available

- **Download:**
 - ⦿ <http://research.microsoft.com/projects/HAVOC>
- **Has more details**
 - ⦿ **How to check properties of linked lists and arrays**
 - ⦿ **Type checking for C using SMT solvers**
 - ⦿ **Case studies**

Summary

- **Pros**

- **Scalable**: Modular checking (one procedure at a time)
- **Precision**: Abstract only at procedure/loop boundaries
- **Expressive**: Easy to encode new properties

- **Cons**

- Requires annotations

- **[Research] Need to automate more for a given class of properties**

- E.g. SALINFER [Hacket et al.06] tool for inferring buffer annotations for buffer overrun checking at Microsoft

Next parts: automated techniques

- **Loop invariant generation**
 - ⊙ **Abstract interpretation**
 - ⊙ **Predicate-abstraction with refinement**
- **Bounded model checking**
 - ⊙ **Sacrifice soundness for automation**
 - ⊙ **Does not require loop invariants/procedure contracts**

Questions?