

Lecture 3

①

We will now briefly review the mathematical structure of QM, as well as the Dirac notation widely used in QIT. For this week, we will consider the case where our quantum systems are in completely known states, and well-isolated from any external environment — the pure state case. Next week, we will review how to include both noise and incomplete information in our description — the mixed state or density matrix case.

As we will see later, we can often map a noisy protocol onto an equivalent pure state protocol. This trick, called purification, can often simplify the mathematics, but it can also in some cases give extra insight: we explicitly include the external environment into which information is lost.

The mathematical structure of QM can be described by a set of four postulates. We will introduce these one at a time, along with the necessary notation.

Postulate 1: The state of any physical system is described by a d -dimensional complex vector in the Hilbert space \mathbb{C}^d . ②

For this introduction we will just look at the simplest case of $d=2$: a quantum bit or qubit. Later we will see how to generalize straight forwardly to $d > 2$.

We write the state of a qubit as a column vec:

$$|\psi\rangle \equiv \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \alpha |0\rangle + \beta |1\rangle$$

"ket vector" label probability amplitudes standard orthonormal basis vectors:
 ← This is a superposition of $|0\rangle$ and $|1\rangle$ ← "the Z basis"

$$|0\rangle \equiv \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad |1\rangle \equiv \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

The probability amplitudes α and β are complex numbers. If $|\psi\rangle$ is normalized then

$|\alpha|^2 + |\beta|^2 = 1$

these are the probabilities of the outcomes for the standard basis (Z) measurement. Any choice of basis corresponds to some measurement.

For the qubit (but not a general d -vector) ^③ there is a mapping from states $|\psi\rangle$ to points on the surface of a 3D Bloch sphere.

First note: global phases are physically irrelevant. So $|\psi\rangle$ and $e^{i\theta}|\psi\rangle$ represent the same physical state.

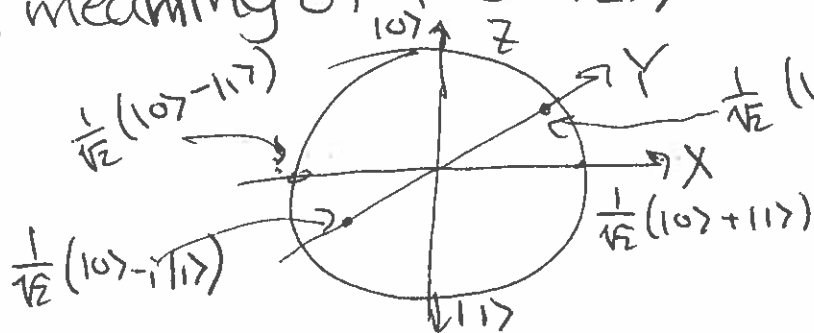
This means that we can choose to make α real.
 e.g., $|\psi\rangle = \alpha|0\rangle + \beta|1\rangle = r_0 e^{i\phi_0}|0\rangle + r_1 e^{i\phi_1}|1\rangle$
 is equivalent to $e^{-i\phi_0}|\psi\rangle = r_0|0\rangle + r_1 e^{i(\phi_1 - \phi_0)}|1\rangle$.

Second note: Normalization $|\alpha|^2 + |\beta|^2 = 1$ means we can parametrize α and β by two angles:

$$\alpha = \cos(\theta/2) \quad 0 \leq \theta \leq \pi$$

$$\beta = \sin(\theta/2) e^{i\phi} \quad 0 \leq \phi \leq 2\pi$$

↑
 The choice of $\theta/2$ here means that the points (θ, ϕ) uniquely cover the surface of a sphere. (There is also a physical meaning of the '1/2'.)



orthogonal states are 180° apart.

The corresponding row vectors (or 1-forms) are \oplus
written

$$\langle \psi | = (|\psi\rangle)^\dagger = (\alpha^* \ \beta^*) \leftarrow \text{"bra vector"}$$

The inner product is written as a "bra"
times a "ket" — a "bracket":

$$|\psi\rangle = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \quad |\phi\rangle = \begin{pmatrix} \gamma \\ \delta \end{pmatrix}$$

$$\langle \phi | \psi \rangle = (\gamma^* \ \delta^*) \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \gamma^* \alpha + \delta^* \beta.$$

$$\langle \psi | \psi \rangle = |\alpha|^2 + |\beta|^2 = 1 \leftarrow \text{normalized!}$$

We can use the inner product to extract
the prob. amplitudes in any orthonormal basis;
e.g.; $\langle 0 | \psi \rangle = \alpha$, $\langle 1 | \psi \rangle = \beta$.

There are only many bases. Some are
used frequently, e.g.;

$$|\pm\rangle = \frac{1}{\sqrt{2}}(|0\rangle \pm |1\rangle) \leftarrow \text{"X basis"}$$

$$\langle \pm | \psi \rangle = \frac{\alpha \pm \beta}{\sqrt{2}}.$$

In addition to state vectors, there are linear transformations, or operators, written (or represented) as $d \times d$ matrices; ⑤

e.g., $\hat{O} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, $\hat{O}^\dagger = \begin{pmatrix} a^* & c^* \\ b^* & d^* \end{pmatrix}$
↑
 Hermitian conjugate.

Matrices are often expressed in terms of outer products: $|\psi\rangle\langle\phi|$ is a $d \times d$ matrix.

In terms of a basis

$(|\psi\rangle\langle\phi|)^\dagger = |\phi\rangle\langle\psi|$

$\hat{O} = \sum_{ij} o_{ij} |i\rangle\langle j| = a|0\rangle\langle 0| + b|0\rangle\langle 1| + c|1\rangle\langle 0| + d|1\rangle\langle 1|$
↑ matrix elt.s
↑ basis for $d \times d$ matrices
↑ from example above.

If $|\psi\rangle$ is normalized, then $|\psi\rangle\langle\psi|$ is a rank-one projector:

$(|\psi\rangle\langle\psi|)^2 = |\psi\rangle\langle\psi|\underbrace{\langle\psi|\psi\rangle}_1 = |\psi\rangle\langle\psi|$

$(|\psi\rangle\langle\psi|)^\dagger = |\psi\rangle\langle\psi| \leftarrow$ Hermitian.

Multiplying by a projector picks out a component in a particular subspace.

$|0\rangle\langle 0|\psi\rangle = \alpha|0\rangle$, $|1\rangle\langle 1|\psi\rangle = \beta|1\rangle$, $|\pm\rangle\langle\pm|\psi\rangle = \frac{\alpha \pm \beta}{\sqrt{2}}|\pm\rangle$.

The usual matrix multiplication rules apply. Most matrices do not commute: ⑤

$$[A, B] \equiv AB - BA \leftarrow \text{"commutator"}$$

$$\{A, B\} \equiv AB + BA \leftarrow \text{"anticommutator"}$$

In the 2×2 case, a widely used set of matrices are I, X, Y, Z :

$$I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$Y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$$

$$Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

X, Y and Z are the Pauli matrices. I, X, Y and Z are an orthogonal basis for the 2×2 matrices:

$$(A|B) \equiv \text{Tr} \{A^\dagger B\} \leftarrow \text{The trace of a square matrix is the sum of the diagonal elements.}$$

The Pauli matrices are Hermitian, Unitary, square to the identity, and have eigenvalues ± 1 . They anticommute with each other, and have the algebraic properties

$$XY = iZ, \quad YZ = iX, \quad ZX = iY.$$

The matrices are also traceless: the trace is the sum of the eigenvalues, and $(+1) + (-1) = 0$.

Unitary transformations on a single qubit (2x2) are often called quantum gates. Note that the Paulis (X, Y, Z) are all quantum gates.

A commonly used gate is the Hadamard:

$$H = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

H switches between the X and Z bases:

$$\begin{aligned} H|0\rangle &= |+\rangle, & H|1\rangle &= |-\rangle, \\ H|+\rangle &= |0\rangle, & H|-\rangle &= |1\rangle. \end{aligned}$$

The most general 2x2 unitary takes the form of a rotation on the Bloch sphere:

$$R_{\vec{n}}(\theta) = e^{i(\theta/2)\vec{n} \cdot \vec{\sigma}} \quad \vec{n} = (n_x, n_y, n_z)$$

$$\vec{n} \cdot \vec{\sigma} = n_x X + n_y Y + n_z Z$$

up to a global phase

this means that $(\vec{n} \cdot \vec{\sigma})^2 = I \rightarrow n_x^2 + n_y^2 + n_z^2 = 1$

Special cases are rotations around the X, Y, and Z axes

$$R_x(\theta) = e^{i(\theta/2)X}, \quad R_y(\theta) = e^{i(\theta/2)Y}, \quad R_z(\theta) = e^{i(\theta/2)Z}$$