

Wiener Chaos Solution of Stochastic Evolution Equations

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The Wiener Chaos

$(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, \mathbb{P})$, $W(t) = (w_k(t), k \geq 1)$.

$\{m_i(s), i \geq 1\}$ — CONS in $L_2([0, T])$,

$$\xi_{ik} = \int_0^T m_i(s) dw_k(s).$$

$$J = \left\{ \alpha = (\alpha_i^k, i, k \geq 1) \mid |\alpha| = \sum_{i,k} \alpha_i^k < \infty \right\};$$

$$\xi_\alpha = \prod_{i,k} \left(\frac{H_{\alpha_i^k}(\xi_{ik})}{\sqrt{\alpha_i^k!}} \right), \text{ where}$$

$H_n(x) = (-1)^n e^{x^2/2} \frac{d^n}{dx^n} e^{-x^2/2}$. Note: if $|\alpha| = 0$, then $\xi_\alpha = 1$.

Theorem. (Cameron & Martin, 1947)

The collection $\{\xi_\alpha, \alpha \in J\}$ is an orthonormal basis in $L_2(\Omega, \mathcal{F}_T^W, \mathbb{P})$:

If $\eta \in L_2(\Omega, \mathcal{F}_T^W, \mathbb{P})$ and $\eta_\alpha = \mathbb{E}(\eta\xi_\alpha)$, then

$$\eta = \sum_{\alpha \in J} \eta_\alpha \xi_\alpha$$

and

$$\mathbb{E}|\eta|^2 = \sum_{\alpha \in J} \eta_\alpha^2.$$

A Technical Lemma

Lemma. Define $\xi_\alpha(t) = \mathbb{E}(\xi_\alpha | \mathcal{F}_t^W)$. Then

$$d\xi_\alpha(t) = \sum_{i,k} \sqrt{\alpha_i^k} \xi_{\alpha^-(i,k)}(t) m_i(t) dw_k(t),$$

where $\alpha^-(i,k)$ is the multi-index with the components

$$\left(\alpha^-(i,k)\right)_j^l = \begin{cases} \max(\alpha_i^k - 1, 0), & \text{if } i = j \text{ and } k = l, \\ \alpha_j^l, & \text{otherwise.} \end{cases}$$

Note: If $|\alpha| = 0$, then $\xi_\alpha(t) = 1$ for all $t \geq 0$. Otherwise, $\xi_\alpha(0) = 0$.

Example 1: SPDE With a Classical Solution

$$\begin{aligned} du(t, x) &= 1 \cdot u_{xx}(t, x)dt + 1 \cdot u_x(t, x)dw(t), \\ t > 0, x \in \mathbb{R}, u(0, x) &= \varphi(x) \in L_2(\mathbb{R}). \\ 1 - 0.5 \cdot 1^2 &= 0.5 > 0. \end{aligned}$$

Fact: $\sup_{0 < t < T} \mathbb{E} \|u\|_{L_2(\mathbb{R})}^2(t)$

$$+ \frac{1}{2} \int_0^T \mathbb{E} \|u_x\|_{L_2(\mathbb{R})}^2(s) ds \leq \|\varphi\|_{L_2(\mathbb{R})}^2.$$

Then $u(t, x) = \sum_{\alpha \in J} u_\alpha(t, x) \xi_\alpha.$

Example 1: The S-system

One Wiener process, so $\alpha = (\alpha_i, i \geq 1)$.

$$d\xi_\alpha(t) = \sum_i \sqrt{\alpha_i} \xi_{\alpha-(i)}(t) m_i(t) dw(t),$$

$$\xi_\alpha(0) = I(|\alpha| = 0);$$

$$du(t, x) = u_{xx}(t, x)dt + u_x(t, x)dw(t).$$

By \mathcal{F}_t^W -measurability of u , $u_\alpha(t, x) = \mathbb{E}(u(t, x)\xi_\alpha(t))$;

$$\dot{u}_\alpha = (u_\alpha)_{xx} + \sum_i \sqrt{\alpha_i} (u_{\alpha-(i)})_x m_i(t),$$

$$u_\alpha(0, x) = \varphi(x)I(|\alpha| = 0).$$

Also, $\sup_{0 < t < T} \sum_{\alpha \in J} \|u_\alpha\|_{L_2(\mathbb{R})}^2(t)$

$$+ \frac{1}{2} \sum_{\alpha \in J} \int_0^T \|(u_\alpha)_x\|_{L_2(\mathbb{R})}^2(s) ds \leq \|\varphi\|_{L_2(\mathbb{R})}^2.$$

The WC Method

Equation \Rightarrow S-System \Rightarrow Solution of the
S-System

\Rightarrow The **Winer Chaos Solution** of the
Equation as a (Formal) Fourier Series.

Theorem. *If the Wiener Chaos solution belongs to the traditional solution space, then it is a traditional solution.*

For $du = u_{xx}dt + u_xdw(t)$, traditional solution means $(u, \psi)(t) = (\varphi, \psi) - \int_0^t (u_x, \psi_x)(s)ds + \int_0^t (u_x, \psi)(s)dw(s)$, $\psi \in C_0^\infty(\mathbb{R})$.

Example 2: SPDE Without Classical Solution

$$du(t, x) = u_{xx}(t, x)dt + 2u_x(t, x)dw(t),$$

$$t > 0, x \in \mathbb{R}, u(0, x) = \varphi(x).$$

No classical solution: $1 - 0.5 \cdot (2^2) = -1 < 0$.

Wiener Chaos solution: $u(t, x) = \sum_{\alpha} u_{\alpha}(t, x)\xi_{\alpha}$,

$$\dot{u}_{\alpha} = (u_{\alpha})_{xx} + 2 \sum_i \sqrt{\alpha_i} (u_{\alpha - (i)})_x m_i(t),$$

$$u_{\alpha}(0, x) = \varphi(x)I(|\alpha| = 0).$$

Now $\sum_{\alpha \in J} \|u_{\alpha}\|_{L_2(\mathbb{R})}^2(t) = \infty, t > 0$, but

$$\sup_{0 < t < T} \sum_{k \geq 0} 4^{-k} \sum_{|\alpha|=k} \|u_{\alpha}\|_{L_2(\mathbb{R})}^2(t) < \|\varphi\|_{L_2(\mathbb{R})}^2.$$

The S-System

Hilbert spaces $\mathbf{H}_s, \mathbf{H}_f, \mathbf{H}_i$.

Operators $\mathcal{A}, \mathcal{M}_k : \mathbf{H}_s \rightarrow \mathbf{H}_f$.

Assume

$$\dot{v}(t) = \mathcal{A}v(t) + f(t)$$

has a unique solution $v \in L_2((0, T); \mathbf{H}_s)$ for every $f \in L_2((0, T); \mathbf{H}_f)$ and $v(0) \in \mathbf{H}_i$.

$$\begin{cases} \dot{u}_\alpha(t) = \mathcal{A}u_\alpha(t) + \sum_{i,k} \sqrt{\alpha_i^k} \mathcal{M}_k u_{\alpha-(i,k)}(t) m_i(t), \\ u_\alpha(0) = u_0 I(|\alpha| = 0) \in \mathbf{H}_i. \end{cases}$$

$u(t) = \sum_{\alpha} u_\alpha(t) \xi_\alpha$ — *Wiener Chaos solution* of

$$du(t) = \mathcal{A}u(t)dt + \sum_{k \geq 1} \mathcal{M}_k u(t) dw_k(t),$$

$$u(0) = u_0.$$

Solving the S-System

Theorem. *Assume that the operator A generates a semi-group $(\mathbb{T}_t, t \geq 0)$ so that, for $t > 0$, the operators \mathbb{T}_t and $\mathcal{M}_k \mathbb{T}_t$ are bounded in a Hilbert space \mathbf{H} . Let $u_0 \in \mathbf{H}$.*

Then, for every $N \geq 0$ and $0 < t < T$,

$$\begin{aligned} & \sum_{|\alpha|=N} \|u_\alpha\|_{\mathbf{H}}^2(t) \\ &= \sum_{k_1, \dots, k_N} \int_0^t \int_0^{s_N} \cdots \int_0^{s_2} \\ & \quad \|\mathbb{T}_{t-s_N} \mathcal{M}_{k_N} \cdots \mathbb{T}_{s_2-s_1} \mathcal{M}_{k_1} \mathbb{T}_{s_1} u_0\|_{\mathbf{H}}^2 ds_1 \cdots ds_N. \end{aligned}$$

Example 3

$$du(t, x) = u_{xx}(t, x)dt + b(x)u_x(t, x)dw(t),$$

$$t > 0, x \in \mathbb{R}, u(0, x) = \varphi(x) \in L_2(\mathbb{R}),$$

$$b = b(x) \text{--- measurable, } \sup_{x \in \mathbb{R}} |b(x)|^2 \leq 2.$$

Then $\mathcal{M} = b(x)\partial/\partial x$ and

$$\sum_{|\alpha| \leq N} \|u_\alpha\|_{L_2(\mathbb{R})}^2(t)$$

$$\leq \|\varphi\|_{L_2(\mathbb{R})}^2 - \int_0^t \int_0^s \int_0^{s_N} \cdots \int_0^{s_2}$$

$$\|\mathcal{M}\mathbb{T}_{t-s_N}\mathcal{M}\cdots\mathbb{T}_{s_2-s_1}\mathcal{M}\mathbb{T}_{s_1}\varphi\|_{L_2(\mathbb{R})}^2 ds_1 \cdots ds_N ds.$$

In particular, $\sum_{\alpha} \|u_\alpha\|_{L_2(\mathbb{R})}^2(t) \leq \|\varphi\|_{L_2(\mathbb{R})}^2$ and $u(t) \in L_2(\Omega; L_2(\mathbb{R}))$ for all $t \in [0, T]$.

Weighted Wiener Chaos

Idea: replace w_k with $q_k w_k$.

$Q = \{q_1, q_2, \dots\}$, $q_k > 0$; $Q \leq \tilde{Q}$ means $q_k \leq \tilde{q}_k$ for all k ;

$$q^\alpha = \prod_{i,k} q_k^{\alpha_i^k}.$$

Definition. For a Banach space X , the Q -weighted Wiener Chaos space $L_{2,Q}(\mathcal{F}_T^W; X)$ is

$$L_{2,Q}(\mathcal{F}_T^W; X) = \left\{ (u_\alpha) : \sum_{\alpha \in J} q^{2\alpha} \|u_\alpha\|_X^2 < \infty \right\}.$$

$$Q = 1 \Rightarrow L_{2,Q}(\mathcal{F}_T^W; X) = L_2(\mathcal{F}_T^W; X);$$

$$Q \leq \tilde{Q} \Rightarrow L_{2,\tilde{Q}}(\mathcal{F}_T^W; X) \subseteq L_{2,Q}(\mathcal{F}_T^W; X).$$

Example 4: $w_k \rightarrow q_k w_k$

1. (Obvious) If $u(t) = 1 + \sum_{k \geq 1} \int_0^t u(s) dw_k(s)$,

then $u \in L_{2,Q}(\mathcal{F}_T^W; \mathbb{R})$ for every $Q = (q_1, q_2, \dots)$
so that
$$\sum_{k \geq 1} q_k^2 < \infty.$$

2. (Nualart-Rozovskii, 1997) If

$$du(t, x) = \Delta u(t, x) dt + u(t, x) dw(t, x),$$

$$t > 0, x \in \mathbb{R}^d, d \geq 2,$$

then $u \in L_{2,Q}(\mathcal{F}_T^W; L_2(\mathbb{R}^d))$ for some Q .

Theorem. Consider

$$\begin{aligned} du(t, x) &= u_{xx}(t, x)dt + b(x)u_x(t, x)dw(t), \\ t > 0, x \in \mathbb{R}, u(0, x) &= \varphi(x) \in L_2(\mathbb{R}), \\ b = b(x) &\text{— bounded, measurable;} \\ Q &= (q, 1, 1, \dots), q > 0. \text{ Then} \end{aligned}$$

$$u(t) \in L_{2,Q}(\mathcal{F}_T^W; L_2(\mathbb{R})) \Leftrightarrow q^2 \sup_{x \in \mathbb{R}} |b(x)|^2 < 2.$$

If $\sup_{x \in \mathbb{R}} |b(x)|^2 < 2$, then $u(t) \in L_{2,Q}(\mathcal{F}_T^W; L_2(\mathbb{R}))$

for some $q > 1$.

If $\sup_{x \in \mathbb{R}} |b(x)|^2 \geq 2$, then $u(t) \in L_{2,Q}(\mathcal{F}_T^W; L_2(\mathbb{R}))$

for some $q < 1$.

S-Transform

$$h(t) = (h_1(t), \dots, h_n(t));$$

$$\mathcal{E}(h) = \exp \left\{ \sum_k \int_0^T h_k(t) dw_k(t) - \frac{1}{2} \sum_k \|h_k\|_{L_2((0,T))}^2 \right\}$$

If $h_k(t) = \sum_{i=1}^{n_k} h_{ik} m_i(t)$, then $(\mathcal{E}(h))_\alpha = \prod_{i,k} \frac{h_{ik}^{\alpha_i^k}}{\sqrt{\alpha_i^k}}$;

$\|\mathcal{E}(h)\|_{L_{2,Q}(\mathcal{F}_T^W; \mathbb{R})}^2 = \exp \left\{ \sum_{i,k} h_{i,k}^2 q_k^2 \right\} < \infty$ for every Q . For $u \in L_{2,Q}(\mathcal{F}_T^W; X)$ can then define

$$u_h = \sum_\alpha u_\alpha (\mathcal{E}(h))_\alpha \text{ — S-transform of } u .$$

Definition. *Soft solution of*

$$du(t) = \mathcal{A}u(t)dt + \sum_{k \geq 1} \mathcal{M}_k u(t) dw_k(t)$$

means $\dot{u}_h(t) = \mathcal{A}u_h(t) + \sum_{k \geq 1} h_k(t) \mathcal{M}_k u_h(t)$.

Theorem. *If $u \in L_{2,Q}(\mathcal{F}_T^W; X)$ for some Q , then the soft solution is equivalent to the Wiener Chaos solution.*

- To study the properties of the solution, it is easier to work with (u_α) than with u_h .
- Can have Wiener Chaos solution that belongs to no $L_{2,Q}$.

Example 5

$$\boxed{du(t, x) = u_x(t, x)dw(t),}$$

$$t > 0, x \in \mathbb{R}, u(0, x) = \varphi(x) \in \mathcal{S}(\mathbb{R}).$$

Then

$$\sum_{|\alpha|=N} \|u_\alpha\|_{L_2(\mathbb{R})}^2(t) = \frac{t^N}{N!} \|\varphi_x^{(N)}\|_{L_2(\mathbb{R})}^2.$$

- $\|\varphi_x^{(N)}\|_{L_2(\mathbb{R})}^2 \leq C^N \sqrt{N!} \Rightarrow u(t) \in L_2(\Omega; L_2(\mathbb{R})).$
- $\|\varphi_x^{(N)}\|_{L_2(\mathbb{R})}^2 \sim C^N N! \Rightarrow u(t) \in L_{2,Q(t)}(\Omega; L_2(\mathbb{R})).$
- $\|\varphi_x^{(N)}\|_{L_2(\mathbb{R})}^2 \geq e^{aN^2} \Rightarrow u(t) \notin L_{2,Q}(\Omega; L_2(\mathbb{R})).$

References

Wiener Chaos: Wiener (1930's), Cameron & Martin (1947), Hida et al. (1993), Øksendal et al. (1996)

S-transform: Kondratiev et al. (1996)

SODE: Krylov & Veretennikov (1976)

Filtering: Wong (1981), Ocone (1983), Mikulevicius & Rozovskii (1993), Budhiraja & Kallianpur (1996)

Flows: LeJan and Raimond (2002)

Soft Solutions: Mikulevicius & Rozovskii (1994), Nualart & Rozovskii (1997), Potthoff et al. (1998)

Navier-Stokes equation: Mikulevicius & Rozovskii (2001)

So What?

- Have a pretty general procedure for constructing solutions for linear equation.
- S-system is often more convenient than the underlying equation.
- Big plans for the NS equation.